

Decomposing data-fields with multiple transports using neural implicit flow

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Context

Finding low-rank structures in dynamical systems

- Derive **low-rank surrogate models**
↪ Kolmogorov n -width problem [2]

• Separate and analyze the different components
Low-rank structures appear under certain transformations (a.k.a transports)

Applications:

- Model order reduction (e.g. wildland fire model, turbulence)
- Low-rank denoising (tomography)

sPOD: A nonlinear and low-rank decomposition

Goal: Decomposing the data $q(x, t)$ into low-rank surrogate

$$q(x, t) \approx \sum_{k=1}^K \mathcal{T}^k q^k(x, t).$$

where

$$q^k(x, t) \approx \sum_{r=1}^{R_k} \alpha_r^k(t) \phi_r^k(x),$$

Solution: When $\{\mathcal{T}^k\}$ are known, there exist efficient algorithm to determine $\{q^k\}$ [1].

Issues and objectives

- Issues:**
- In real-life applications, $\{\mathcal{T}^k\}$ are hard to determine
 - Non-convex optimization
 - Alternating optimization on $\{q^k\}$ and $\{\mathcal{T}^k\}$ fails
- Object:** Learn $\{\mathcal{T}^k\}$ and $\{q^k\}$ jointly using a dual neural network approach

Optimization problem formulation

Minimizing the **loss function:**

$$\mathcal{L}(\{\mathbf{Q}^k\}, \{\mathbf{T}^k\}) \stackrel{\text{def}}{=} \left\| \mathbf{Q} - \sum_{k=1}^K \mathbf{T}^k \mathbf{Q}^k \right\|_F^2 + \lambda \sum_{k=1}^K \|\mathbf{Q}^k\|_*.$$

where $\mathbf{Q}^k = (q^k(x_m, t_n))_{m,n} \in \mathbb{R}^{M \times N}$ and $\mathbf{T}^k \mathbf{Q}^k = ((\mathcal{T}^k q^k)(x_m, t_n))_{m,n} \in \mathbb{R}^{M \times N}$
↪ Discretizing the transformed data to avoid interpolation error

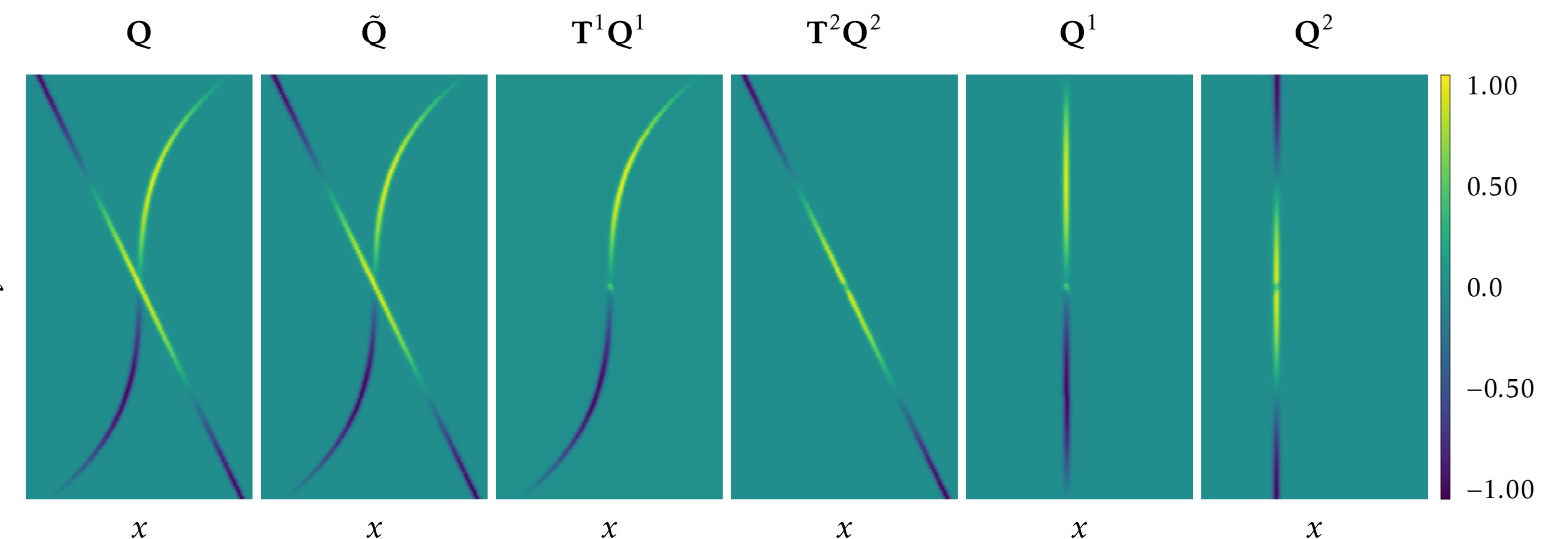
Results

- **Synthetic data:** q = superposition of 2 Gaussian waves

$$q(x, t) = \sin(t) f(x - \Delta^1(t)) + \cos(t) f(x - \Delta^2(t)) \quad \text{with } f(x) = \exp(-(x - 200)^2/4^2)$$

$$\text{Shifts: } \Delta^1(t) = 0.15t^3 + 0.8t + 1.5 \text{ and } \Delta^2(t) = -18t + 2$$

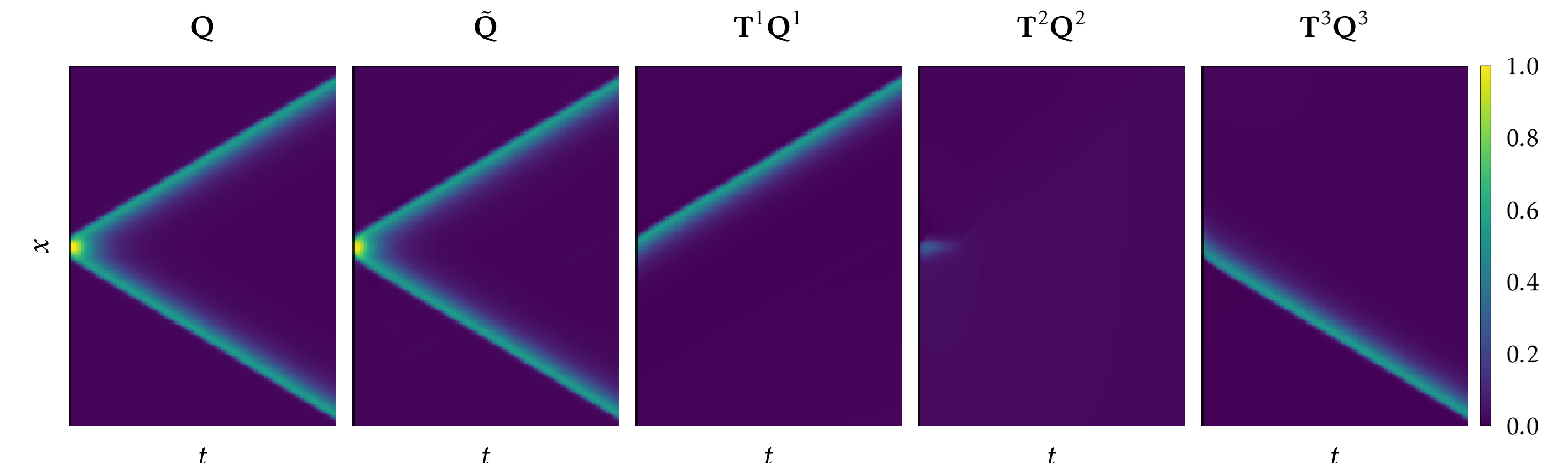
Discretization: $M = 400$ and $N = 200$



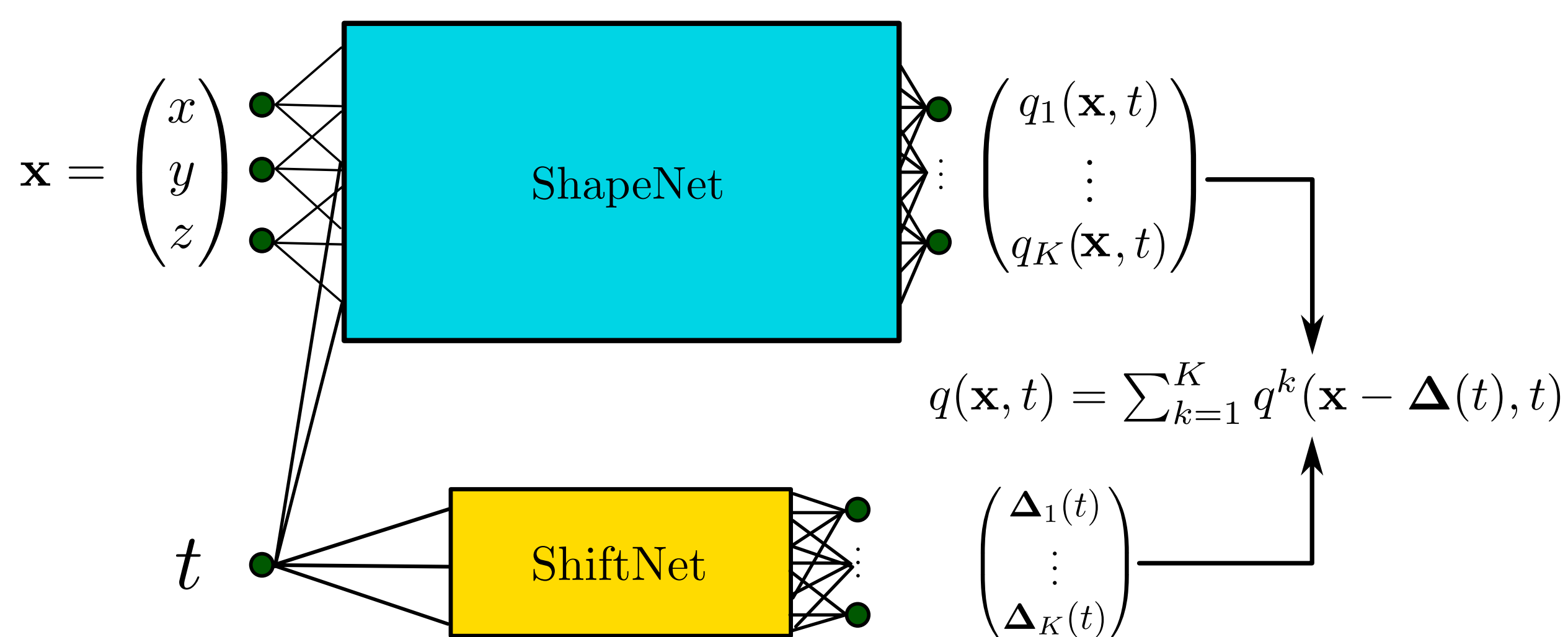
- **Wildlandfire model:** q solutions of: (2 fields $q \rightsquigarrow 1$ for T and 1 for S)

$$\begin{cases} \partial_t T = \nabla \cdot (k \nabla T) - v \nabla T + \alpha S r(\mu, T, T_a) - \gamma(T - T_A) \\ \partial_t S = -S \delta(T, \mu, T_a) \end{cases}$$

Discretization: $M = 500$ and $N = 500$



NsPOD: Neural sPOD using neural implicit flow



Networks = 3 Hidden fully-connected layers interleaved with ELU

Assumption: $\{\mathcal{T}^k\}$ are simple shifts $\Delta^k(t)$

Main idea: Separating spatial elements from time
(or other parameters external to space)

- ShapeNet: model the output fields $\{q^k\}$ as functions of space (\approx PINNs)
- Shiftnet: model the transport $\{\mathcal{T}^k\}$ and modulate ShapeNet by changing the space parameters in ShapeNet

Training

- **Benefits of NsPOD description:**

1. Data points = points $\{(x_m, t_m, q(x_m, t_m))\}$ of the discretization grid
↪ Cheaper than using a full column of \mathbf{Q} in the standard full discrete formulation of sPOD
↪ **Break the curse of dimensionality**
2. Training can be performed on points from random or irregular batches
↪ Training can be performed on mesh agnostic data

- **Non-differentiable loss function**

↪ Require using subgradients instead of gradients in training phase

Training data are typically obtained by solving PDE or by measurements

Conclusion

- + Good separation capability + flexibility to the data field
- + Continuous setting allows efficient training
- + Do not require initialization of the shifts close to the true shifts
- NsPOD may be unstable and sensitive to initialization

Perspectives:

- Extend NsPOD to other kind of transports (not only shifts)
- Use more complex ShapeNet based on PINNs instead of fully-connected layers networks
- Demonstrate the capability of NsPOD on more complex applications and more complex discretization grids.

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References

- [1] P. Krah, A. Marmin, B. Zorawski, J. Reiss and K. Schneider. A robust shifted proper orthogonal decomposition: Proximal methods for decomposing flows with multiple transports, To appear *SIAM J. Sci. Comput.* (ArXiv [2403.04313]) (2024)
- [2] B. Unger and S. Gugercin. Kolmogorov n -widths for linear dynamical systems, *Adv Comput Math* 45, 2273–2286 (2019). (doi: 10.1007/s10444-019-09701-0)
- [3] B. Zorawski, S. Burela, P. Krah, A. Marmin and K. Schneider. Automated transport separation using the neural shifted proper orthogonal decomposition, ArXiv [2407.17539] (July, 2024)